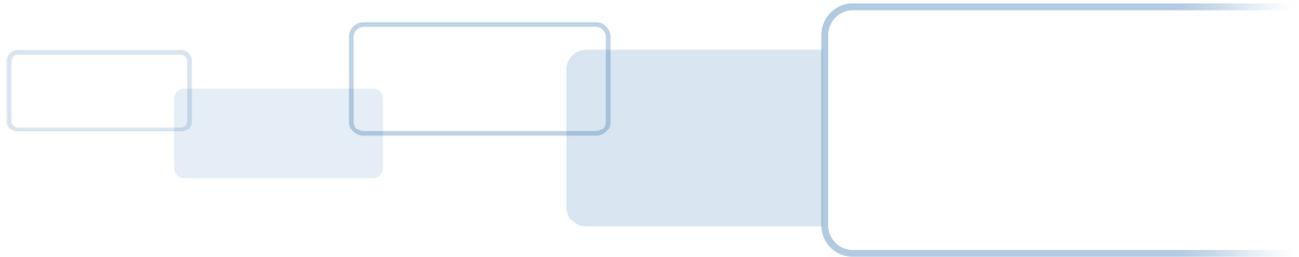




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55x3 PC/SC Driver

USER GUIDE

Driver Version 2.1.1.3

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1 Features

This driver is fully compliant to the PC/SC 2.01.4 specification for contactless Smart cards / Storage cards.

See <http://www.pcscworkgroup.com > Specifications > Download Specifications> for the latest PC/SC Specification.

1.1 Summary

- ISO14443(A/B) cards
- Multiple Antennas
- Multiple Tags per Antenna
- ATR driver
- Get Data command
- Load Keys command
- Authenticate command (PC/SC 2.01.3)
- General Authenticate command
- Read Binary command
- Update Binary command
- Increment command
- Decrement command

1.2 ISO14443(A/B) cards

This driver supports contactless cards, compliant with ISO14443 of type A (part 3 and part 4) and type B, both up to a communication rate of 848 kBit/s on the air interface.

1.3 Multiple Antennas

This driver supports readers with multiple antenna configurations. Furthermore, completely customize the commands that trigger the antenna toggling.

1.4 Multiple Tags per Antenna

Using recent firmware, the driver handles multiple tags on the same antenna at the same time. It also allows the simultaneous reading of multiple tags.

1.5 ATR

This driver constructs ATRs for contactless cards as defined in PC/SC 2.01.4 specification, July 2007, Part 3 - Requirements for PC-Connected Interface Devices, Section 3.1.3.2.3. and further adjusts them for compliance to the next revision of the PC/SC Workgroup specification.

1.6 Get Data command

See to PC/SC 2.01.4 specification, July 2007, Part 3 - Requirements for PC- Connected Interface Devices, Section 3.2.2.1.3.

1.7 PC/SC 2.01.4 compliant Load Keys command

See to PC/SC 2.01.4 specification, July 2007, Part 3 - Requirements for PC- Connected Interface Devices, Section 3.2.2.1.4.

1.8 PC/SC 2.01.3 compliant Authenticate command

See to PC/SC 2.01.3 specification, January 2006, Part 3 - Requirements for PC- Connected Interface Devices, Section 3.2.2.1.5.

Note: This command only supports MIFARE® cards at the moment

1.9 PC/SC 2.01.4 compliant General Authenticate command

See to PC/SC 2.01.4 specification, July 2007, Part 3 - Requirements for PC- Connected Interface Devices, Section 3.2.2.1.5.

Note: This command only supports MIFARE® cards at the moment

1.10 PC/SC 2.01.4 compliant Read Binary command

See to PC/SC 2.01.4 specification, July 2007, Part 3 - Requirements for PC- Connected Interface Devices, Section 3.2.2.1.7.

Note: This command only supports MIFARE® cards at the moment

1.11 PC/SC 2.01.4 compliant Update Binary command

See to PC/SC 2.01.4 specification, July 2007, Part 3 - Requirements for PC- Connected Interface Devices, Section 3.2.2.1.8.

Note: This command only supports MIFARE® cards at the moment

1.12 Increment command

This command increments the value of a block on a storage card.

Command Syntax

Command	Data
CLA	'FF'
INS	'D4'
P1	MSB of block address
P2	LSB of block address
LC	4
Data Field	byte value array indicating block increment
Le	Empty

Response Syntax

	Data		Comment
Data Field	SW1	SW2	Status word as described below
Empty	'90'	'00'	Success
	'65'	'81'	Memory failure (unsuccessful increment)
	'69'	'82'	Security status not satisfied
	'6A'	'82'	Invalid block address
	'6C'	'XX'	Wrong length (wrong number Lc; 'XX' is the exact

Note: This command only supports MIFARE® cards at the moment

1.13 Decrement command

This command decrements the value of a block on a storage card.

Command Syntax

Command	Data
CLA	'FF'
INS	'D8'
P1	MSB of block address
P2	LSB of block address
LC	4
Data Field	byte value array indicating block decrement
Le	Empty

Response Syntax

	Data		Comment
Data Field	SW1	SW2	status word as described below
Empty	'90'	'00'	Success
	'65'	'81'	memory failure (unsuccessful decrement)
	'69'	'82'	security status not satisfied
	'6A'	'82'	invalid block address
	'6C'	'XX'	Wrong length (wrong number Lc; 'XX' is the exact

Note: This command only supports MIFARE® cards at the moment

2 Extended Features

Additional features are implemented into the driver as I/O-Controls. The purpose of these features is to extend the functionality / interoperability and to ease development using a combination of 55x3 readers and this driver.

Features listed are accessible through the included Driver Applet. See individual commands for detailed usage information.

For an example of how to invoke I/O-Controls, see to Appendix – Code Example, page 18.

2.1 Summary

- Query Driver Version
- Query Card
- Query CID
- Get UID
- Query Reader Version
- Query Running
- Set Airspeed
- Query Airspeed
- Query AsyncBaudRates
- Set Timeout
- Query Timeout
- Request Read Settings
- Set ISO14443-4 Support
- Query ISO14443-4 Support
- Set Antenna

2.2 Query Driver Version

This I/O-Control returns the driver's version string in ASCII-Coding.

IOCTL-Code	Input Buffer	Output Buffer size
2065	-	>= 8 bytes recommended

Response

Data	Comment
Char*	Version String

2.3 Query Card

This I/O-Control returns whether a card is available in a requested slot or not.

IOCTL-Code	Input Buffer	Output Buffer size
2050	1 byte	1 byte

Input values

Data	Comment
0x00 - 0xFF	Desired card slot

Response values

Data	Comment
0x00	No card is present
0x01	A card is present

2.4 Query CID

This I/O-Control returns whether the card in a requested slot supports/uses CID or not.

IOCTL-Code	Input Buffer	Output Buffer size
2062	1 byte	1 byte

Input values

Data	Comment
0x00 - 0xFF	Desired card slot

Response values

Data	Comment
0x00	Present card supports CID
0x01	Present card does not support CID

2.5 Get UID

This I/O-Control returns the UID preceded by the tag type of the card in a requested slot.

IOCTL-Code	Input Buffer	Output Buffer size
2304	1 byte	1 byte + UID size

Input values

Data	Comment
0x00 - 0xFF	Desired card slot

Response

Returns the present card's UID preceded by the card's type (1 Byte). The byte-mapping is described in your reader manual within the New Serial Mode section.

2.6 Query Reader Version

This I/O-Control returns the reader's version string in ASCII-Coding.

IOCTL-Code	Input Buffer	Output Buffer size
2053	-	>= 16 bytes recommended

Response

Data	Comment
Char*	Version String

2.7 Query Polling

This I/O-Control returns whether card polling is enabled or not.

IOCTL-Code	Input Buffer	Output Buffer size
2064	-	1 byte

Response values

Data	Comment
0x00	Drivers polling routines have been stopped
0x01	Driver is operating normal and polls card as usual

2.8 Set Airspeed

This I/O-Control sets the reader's current maximum RFID communication baud rate.

IOCTL-Code	Input Buffer	Output Buffer
2070	<code>sizeof(unsigned long)</code>	-

Input values

Data	Comment
0x106 or 0x00	Set maximum baud rate to 106 kBit/s
0x212 or 0x02	Set maximum baud rate to 212 kBit/s
0x424 or 0x04	Set maximum baud rate to 424 kBit/s
0x848 or 0x08	Set maximum baud rate to 848 kBit/s

2.9 Query Airspeed

This I/O-Control returns the reader's current maximum RFID communication baud rate.

IOCTL-Code	Input Buffer	Output Buffer size
2071	-	<code>sizeof(unsigned long)</code>

Response values

Data	Comment
0x106	Maximum baud rate is 106 kBit/s
0x212	Maximum baud rate is 212 kBit/s
0x424	Maximum baud rate is 424 kBit/s
0x848	Maximum baud rate is 848 kBit/s

2.10 Query AsyncBaudRates

IOCTL-Code	Input Buffer	Output Buffer size
2073	-	1 byte

Response values

Data	Comment
0x00	Reader supports asynchronous baud rates
0x01	Reader does not support asynchronous baud rates

2.11 Set Timeout

This I/O-Control sets the reader's current contactless timeout value.

IOCTL-Code	Input Buffer	Output Buffer
2074	sizeof(unsigned long)	-

Input values

Data	Comment
0x00	Automatic values are applied for each card
1 - 19000	Manual timeout in milliseconds

2.12 Query Timeout

This I/O-Control returns the reader's current contactless timeout value in milliseconds.

IOCTL-Code	Input Buffer	Output Buffer size
2075	-	sizeof(unsigned long)

Response value

Data	Comment
0x00	Automatic values are applied for each card
1 - 19000	Current timeout in milliseconds

2.13 Request Read Settings

This I/O-Control advises the driver to reload and apply settings from registry.

IOCTL-Code	Input Buffer	Output Buffer
2076	-	-

2.14 Set ISO14443-4 Support

IOCTL-Code	Input Buffer	Output Buffer
2077	1 byte	-

Note: This I/O-Control has a different behavior than the previous 2.0.X driver series!

Input values

Data	Comment
0x00	Disable ISO14443-4 support
0x01	Enable ISO14443-4 support

2.15 Query ISO14443-4 Support

IOCTL-Code	Input Buffer	Output Buffer
2078	-	1 byte

Note: This I/O-Control has a different behavior than the previous 2.0.X driver series!

Response values

Data	Comment
0x00	ISO14443-4 support is disabled
0x01	ISO14443-4 support is enabled

2.16 Set Antenna

Fixates an antenna and/or advises reader to start/stop toggling.

IOCTL-Code	Input Buffer	Output Buffer
2080	1 byte	-

Input values

Data	Comment
0x00 – 0xXX	Stop toggling and fixate to antenna with the given index.
null OR >= number of	Enable antenna toggling again

3 Virtual COM-Port Interface (VCOM)

55x3 PC/SC Driver also registers a virtual COM-Port interface that behaves like a native COM-Port – although with limited functionality.

The Name of this COM-Port consists of the usual COM prefix (e.g.: COM1, COM3) with a driver specific postfix (e.g.: OK55x3_0, OK55x3_1).

So the resulting VCOM name is: COM_OK55x3_X, where X stands for the device- number.

You can connect to this COM-Port using the standard Win32 function calls like CreateFile and CloseHandle or using a recent ReaderDLL.

Be aware that it is not necessary to detect the reader manually / to switch baud rates, the driver already did this prior to any VCOM connection.

You should have a stable binary connection at the highest baud rate by default.

Note: While a connection to the VCOM port is present, the PC/SC card polling is switched off because it would interfere with user communication.

4 Contactless EMVCo Support

The following functionality is only available for Multi ISO Reader Boards with firmware versions above 1.2.5. Additional features are implemented into the driver as I/O-Controls. The purpose of these features is to extend the functionality / interoperability and to ease development using a combination of 55x3 readers and this driver.

For an example of how to invoke I/O-Controls, see to Appendix – Code Example, page 18.

4.1 Summary

- Set RFID Operation Mode
- Query RFID Operation Mode – TLV encoded
- Query Airspeed

4.2 Set RFID Operation Mode

IOCTL-Code	Input Buffer	Output Buffer size
3107	1 byte	-

Input values

Data	Comment
0x00	Set RFID Operation Mode ISO
0x11	Set RFID Operation Paypass

Response values

SCardControl function call fails with error code 0x1F when reader firmware doesn't support Contactless EmvCo functionality.

4.3 Query RFID Operation Mode

IOCTL-Code	Input Buffer	Output Buffer size
3200	-	>=9 byte

Response

Data	Comment
Byte*	TLV encoded byte stream

The response of this request is a TLV encoded byte stream:

TLV decoding structure:

Type (1byte) Length (1 byte) Value(s)

Defined TLV Tags:

TLV_TAG_VERSION_PAYPASS_LIBRARY	0xB3 (hex)
TLV_TAG_READER_OPERATION_MODE	0xB6 (hex)

Defined return values for 'Operation Mode Tag':

OP_MODE_RFID_ISO	0x10 (hex)
------------------	------------

4.4 Query PayPass Library Version

IOCTL-Code	Input Buffer	Output Buffer size
3200	-	>=9 byte

Response

Data	Comment
Byte*	TLV encoded byte stream

The response of this request is a TLV encoded byte stream:

TLV decoding structure:

Type (1byte) Length (1 byte) Value(s)

Defined TLV Tags:

TLV_TAG_VERSION_PAYPASS_LIBRARY	0xB3 (hex)
---------------------------------	------------

Defined return values for PayPass Library Version:

Byte:	Definition:	Range:
1:	PAYPASS_LIB_MAJOR_VERSION	0 - 255 (dec)
2:	PAYPASS_LIB_MINOR_VERSION	0 - 255 (dec)
3:	PAYPASS_LIB_BUILD_NUMBER	0 - 255 (dec)
4:	PAYPASS_LIB_PATCH_NUMBER	0 - 255 (dec)

5 Appendix – Code Example

The following tested code establishes a connection to windows smart card service, enumerates all readers, stores them into an array of defined structures, connects to the first reader found, gets/sets some data and disconnects from both, reader and smart card service.

Include: **winscard.h**
Link: **winscard.lib**

```
// Defines the driver-  
structure struct  
PCSC_Instance  
{  
    // Name of driver instance  
    UCHAR Name[128];  
    // The current connection-mode  
    DWORD Mode;  
    // Handle to the instance  
    SCARDHANDLE Handle;  
};  
  
// Used to filter applicable smartcard devices  
#define DRIVER_STRING     55x3  
  
// Handle to the SmartCard service  
SCARDCONTEXT PCSC_Context;  
  
// List of found driver instances  
PCSC_Instance     *PCSC_Instances;  
  
// Number of driver instances in list  
ULONG             PCSC_NumInstances;  
  
// Temporary variable  
DWORD dw_temp;  
  
// Establish connection to the smartcard-service  
LONG result = SCardEstablishContext(SCARD_SCOPE_USER, NULL, NULL,  
                                    &PCSC_Context);  
  
// Check for error
```

```
if (result != SCARD_S_SUCCESS) {
    return;
}

// Buffer that holds all smartcard reader names
UCHAR buffer[2048];
ULONG buffer_length = sizeof(buffer);

// Pointer to a single reader within the buffer
UCHAR* pReader;

// Enumerate all driver instances
result = SCardListReadersA(PCSC_Context, NULL, (LPSTR)buffer,
                           &buffer_length
                           );

// Check for error
if (result != SCARD_S_SUCCESS) {
    SCardReleaseContext(PCSC_Context
                       ); return;
}

// First of all check how much readers are connected
PCSC_NumInstances = 0;
pReader = buffer;
while (pReader && *pReader)
{
    // Check each smartcard reader's name
    if (_strnicmp((CHAR*)pReader,
                 DRIVER_STRING,
                 min(strlen((CHAR*)pReader),
                     strlen(DRIVER_STRING))) ==
        0)
    {
        // Increment instance count if we found a reader
        PCSC_NumInstances++;
    }
    // Advance to next reader-string
    pReader +=
        strlen((CHAR*)pReader)+1;
}

// Exit if no readers have been
found if (!PCSC_NumInstances) {
```

```

        SCardReleaseContext(PCSC_Context);
    }
    return;
}
// Now that we know how much readers we have, initialize the readers-array
PCSC_Instances = new PCSC_Instance[PCSC_NumInstances];

// Fill the detected readers into reader-
array pReader = buffer;
PCSC_NumInstances = 0;
while (pReader && *pReader)
{
    if (_strnicmp((CHAR*)pReader,
        DRIVER_STRING,
        min(strlen((CHAR*)pReader),
            strlen(DRIVER_STRING))) ==
        0)
    {
        // Store each reader's name
        memcpy(PCSC_Instances[PCSC_NumInstances].Name,
            pReader,
                strlen((CHAR*)pReader));

        // Terminate each name correctly
        PCSC_Instances[PCSC_NumInstances].Name[strlen(
            (CHAR*)pReader)] = '\0';

        // Increment instance count
        PCSC_NumInstances++;
    }

    pReader += strlen((CHAR*)pReader)+1;
}

// Connect to first driver instance
result = SCardConnectA(PCSC_Context,
    (LPCSTR)PCSC_Instances[0].Name,
    SCARD_SHARE_DIRECT, NULL,
    &PCSC_Instances[0].Handle, &dw_temp);

// Exit if we can't connect to
reader if (result !=
SCARD_S_SUCCESS) {
    delete PCSC_Instances;
    SCardReleaseContext(PCSC_Context

```

```
    ); return;
}
// Get Airspeed of first driver instance
DWORD b_length;
result = SCardControl(PCSC_Instances[0].Handle, SCARD_CTL_CODE(2071),
NULL,
                    0, buffer, sizeof(buffer), &b_length);

if (result == SCARD_S_SUCCESS)
{
    switch(*((ULONG*)buffer))
    {
        case 0x106:
            printf(Airspeed = 106 kBit/s\n);
            break;
        case 0x212:
            printf(Airspeed = 212 kBit/s\n);
            break;
        case 0x424:
            printf(Airspeed = 424 kBit/s\n);
            break;
        case 0x848:
            printf(Airspeed = 848 kBit/s\n);
            break;
        default:
            printf(Airspeed Unknown\n);
            break;
    }
}
else {
    printf(Error retrieving airspeed!\n);
}

// Set card timeout of first driver instance
ULONG tout = 5000;
memcpy(buffer, &tout, sizeof(ULONG));
result = SCardControl(PCSC_Instances[0].Handle, SCARD_CTL_CODE(2074),
                    buffer, sizeof(ULONG), NULL, NULL, &b_length);
```

```
if (result == SCARD_S_SUCCESS) {
    printf(timeout set!\n);
}
else {
    printf(timeout setting failed!\n);
}
// Close connection to reader
SCardDisconnect(PCSC_Instances[0].Handle, SCARD_LEAVE_CARD);

delete PCSC_Instances;

// Close connection to smartcard-service
SCardReleaseContext(PCSC_Context);
```